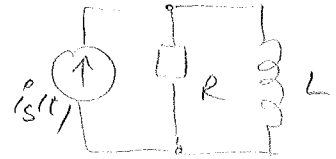
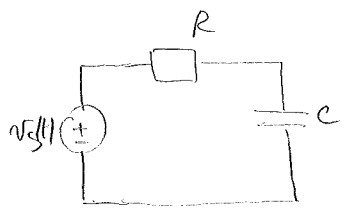


Summary (type of is the number of learning)

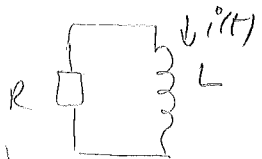
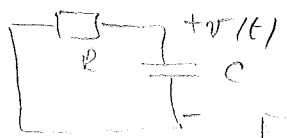


$$\begin{cases} x(t) = v_s(t) \\ \tau = RC \end{cases}$$

$$\tau \frac{dy(t)}{dt} + y(t) = X(t)$$

$$\begin{cases} x(t) = i_s(t) \\ \tau = \frac{L}{R} \end{cases}$$

**(I)**  $x(t) = 0$  Force-free response; natural response



$$v(t) = v(0^+) \cdot e^{-\frac{t}{RC}}$$

$$y(t) = y(0) \cdot e^{-\frac{t}{\tau}}$$

$$i(t) = i(0^+) \cdot e^{-\frac{L}{R}t}$$

We also saw examples of how to create initial values/conditions!

**(II)**  $x(t) \neq 0$

**(A)**  $x(t) = X_s$  dc forcing function

$$y(t) = \underbrace{y(0) \cdot e^{-\frac{t}{\tau}}}_{= y_{\text{natural}}} + \underbrace{X_s (1 - e^{-\frac{t}{\tau}})}_{= y_{\text{forced}}} = y_{\text{natural}} + y_{\text{forced}}$$

Complete response

$$y(t) = \underbrace{[y(0) - y(\infty)] \cdot e^{-\frac{t}{\tau}}}_{= y_{\text{transient}}} + \underbrace{y(\infty)}_{= y_{\text{ss}}} = y_{\text{transient}} + y_{\text{ss}}$$

"Don't forget to include it's not a full!"

**(B)**  $x(t) = X_m \cos \omega t$  ac forcing function.

$$y(t) = \underbrace{y(0) \cdot e^{-\frac{t}{\tau}}}_{= y_{\text{natural}}} + \underbrace{\frac{X_m}{1 + (\omega\tau)^2} (\cos \omega t + \omega\tau \sin \omega t - e^{-\frac{t}{\tau}})}_{= y_{\text{forced}}}$$

Complete response.

$$y(t) = \underbrace{\left[ y(0) - \frac{X_m}{1 + (\omega\tau)^2} \right] e^{-\frac{t}{\tau}}}_{= y_{\text{transient}}} + \underbrace{\frac{X_m}{\sqrt{1 + (\omega\tau)^2}} \cos(\omega t - \tan^{-1} \omega\tau)}_{= y_{\text{ss}} = Y_m \cdot \cos(\omega t + \phi)}$$