

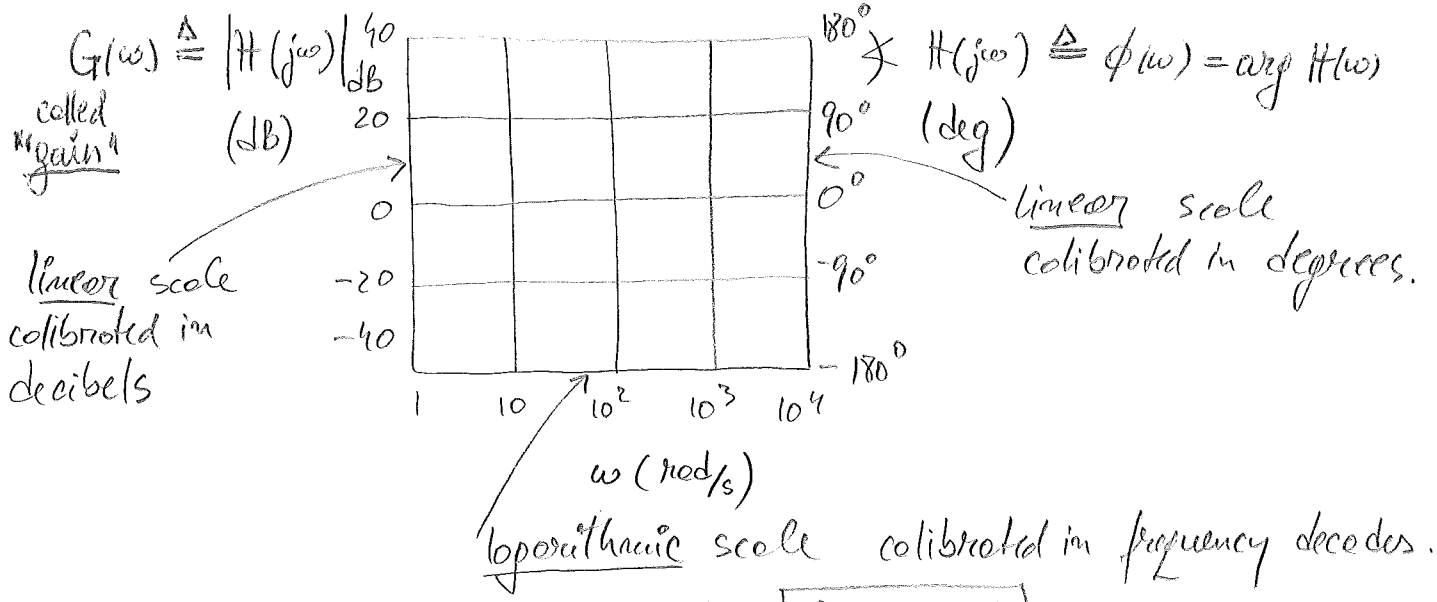
#### 4 BODE DIAGRAMS

- The manner in which the ac response varies with frequency is called frequency response.
- Frequency response can be predicted mathematically using the transfer function  $H(s)$ . First, we derive  $H(s)$  using s-domain techniques; then, we calculate it on the  $j\omega$  axis by letting  $s \rightarrow j\omega$ .
- Frequency response can be visualized graphically by plotting:
  - { - the magnitude  $|H(j\omega)|$
  - { - the phase  $\angle H(j\omega)$  versus  $\omega$ .

#### NOTE

- ac response is the response to an ac signal after all transients have died out. This means that all poles must lie in the left half of the s-plane!
- We saw that location of critical frequencies has a profound impact on the natural response. So, we have good reasons to expect an impact upon the frequency response too!
- We can illustrate the use of  $H(s)$  to:
  - { - locate the critical frequencies in the s-plane
  - { - visualize the frequency response via suitable plots known as Bode plots!
- Note We'll restrict ourselves to network functions of the gain type.

Semi-logarithmic and decibel (dB) scales



- Semi-logarithmic plots are called Bode plots / diagrams (after American Hendrick W. Bode, pronounced 'bodee')
- A frequency decade is called a cycle.
- At times, it is convenient to use the normalized frequency  $\frac{\omega}{\omega_0}$  where  $\omega_0$  is the characteristic frequency of the circuit.

- The decibel value (or dB) of a gain function  $H$  is defined as:

$$|H|_{dB} \triangleq 20 \log_{10} |H| = 10 \log_{10} |H|^2$$

Example:  $20 \log_{10} |-400| = 52 \text{ dB}$

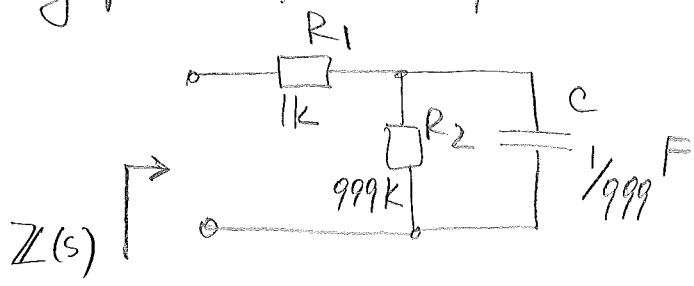
- NOTE**
- unity gain corresponds to 0 dB
  - gain magnitude  $> 1 \Rightarrow$  positive dB's
  - gain magnitude  $< 1 \Rightarrow$  negative dB's.

due to energy considerations

- Properties:
- $|H_1 \cdot H_2|_{dB} = |H_1|_{dB} + |H_2|_{dB}$
  - $\angle(H_1 \cdot H_2) = \angle H_1 + \angle H_2$
  - $|H_1 / H_2|_{dB} = |H_1|_{dB} - |H_2|_{dB}$
  - $\angle(H_1 / H_2) = \angle H_1 - \angle H_2$

Example

Sketch the pole-zero plot and the Bode plots for the driving-point impedance of the one-port:

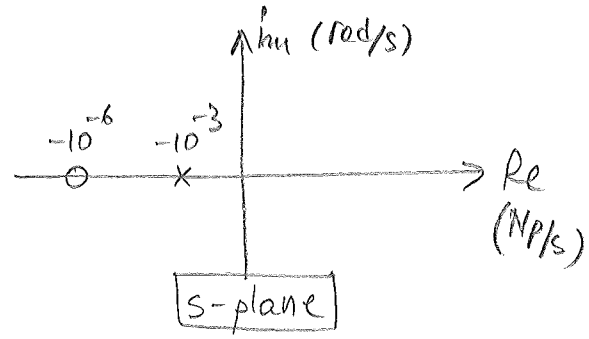


$$Z(s) = R_1 + R_2 \parallel \frac{1}{sC} = (R_1 + R_2) \cdot \frac{(R_1 \parallel R_2)Cs + 1}{R_2Cs + 1} = (R_1 + R_2) \cdot H(s)$$

frequency dependent part of  $Z(s)$

$$H(s) = \frac{\frac{s}{10^6} + 1}{\frac{s}{10^3} + 1}$$

-  $H(s)$  has a zero at  $s = z_1 = -10^6$  Np/s and a pole at  $s = p_2 = -10^3$  Np/s



- To find frequency-response, we let  $s \rightarrow j\omega$ :

$$H(j\omega) = \frac{1 + j \frac{\omega}{10^6}}{1 + j \frac{\omega}{10^3}}$$

$$|H(j\omega)| = \sqrt{\frac{1 + (\frac{\omega}{10^6})^2}{1 + (\frac{\omega}{10^3})^2}}$$

$$|H(j\omega)|_{dB} = 20 \log |H(j\omega)| = 10 \log \frac{1 + (\frac{\omega}{10^6})^2}{1 + (\frac{\omega}{10^3})^2} = 10 \log [1 + (\frac{\omega}{10^6})^2] - 10 \log [1 + (\frac{\omega}{10^3})^2]$$

$$\angle H(j\omega) = \tan^{-1}(\frac{\omega}{10^6}) - \tan^{-1}(\frac{\omega}{10^3})$$

Evaluate these 2 expressions for different values of  $\omega$  to get Bode plots:

