

Lecture 8

BlueTooth

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MARQUETTE
UNIVERSITY

BE THE DIFFERENCE.

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Outline

- BlueTooth
 - Motivation, releases
 - Introduction and Specs
 - Basic Idea
 - Protocol stack
 - Network topology
 - Security
 - Antennas
 - Bluetooth vs. Wi-Fi
- BlueTooth Modules
- Example Application + Demo

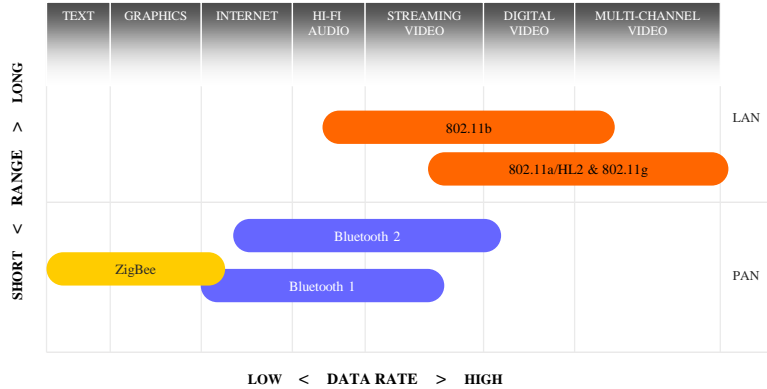
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Wireless Technologies: BlueTooth

- **Bluetooth**

- WiFi
- Cellular
- 3G (3rd Generation)
- UWB (Ultra Wide Band)
- FSO (Free Space Optics)
- WiMAX
- ZigBee
- ...

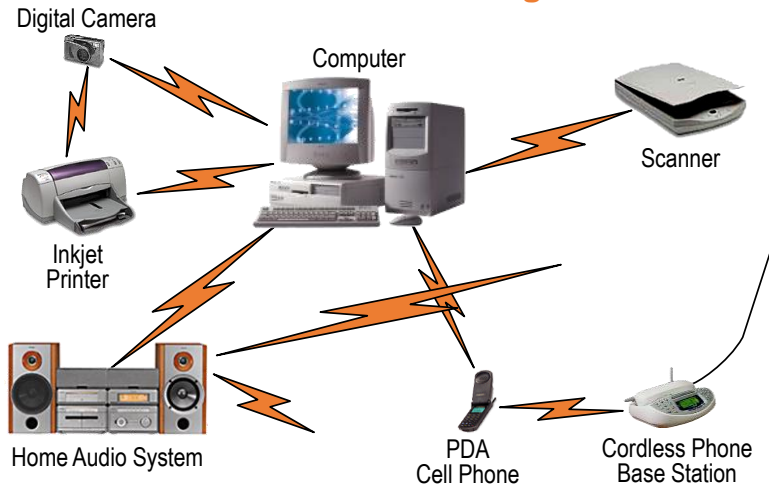


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BlueTooth - Motivation

- **Cable replacement**
- **Ad-hoc networking**



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Requirements

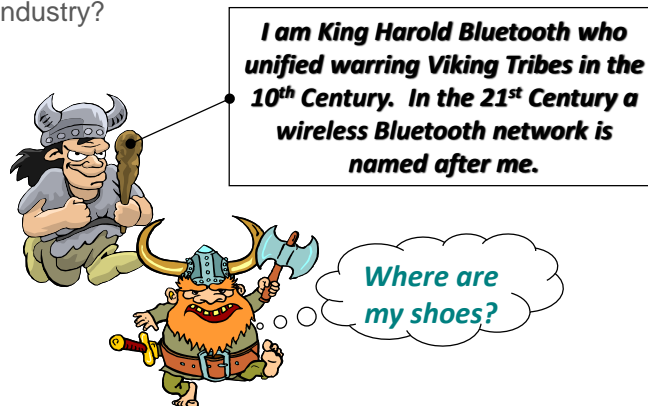
- Low cost as cables – chip \$5
- Must be low power, compact and global
- Secure as cables – must support authentication and encryption
- Must support **both data and voice**
- Must connect to a variety of devices.
- Must support many simultaneous and private “piconets”.
- Must be able to function in a noisy environment.
- Use 2.45GHz radio frequency band – **ISM** (Industrial, Scientific and Medical)

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The Name - Bluetooth?

- The name is attributed to Harald “Blatand” (“Bluetooth”) Gormsen [son of Gorm], King of Denmark in the 10th century
- Choosing this name for the standard indicates how important companies from the Baltic region (nations including Denmark, Sweden, Norway and Finland) are to the communications industry?



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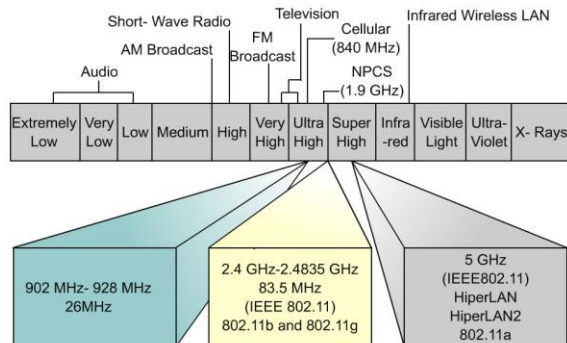
Bluetooth - Introduction

- Bluetooth (BT) is a wireless technology standard
- Invented by Dutch electrical engineer **Jaap Haartsen** working for Ericsson in 1994
- Initially intended as wireless alternative to RS-232 cables
- IEEE 802.15 committee standardized the physical and link layers
- Managed by Bluetooth Special Interest Group (SIG); >40,000 member companies
- Short distances
- Short-wavelength UHF radio waves in **unlicensed ISM (Industrial, Scientific and Medical) band**, 2.400 to 2.485 GHz
- Fixed and mobile devices
- Building personal area networks (PANs)

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US Frequency Bands

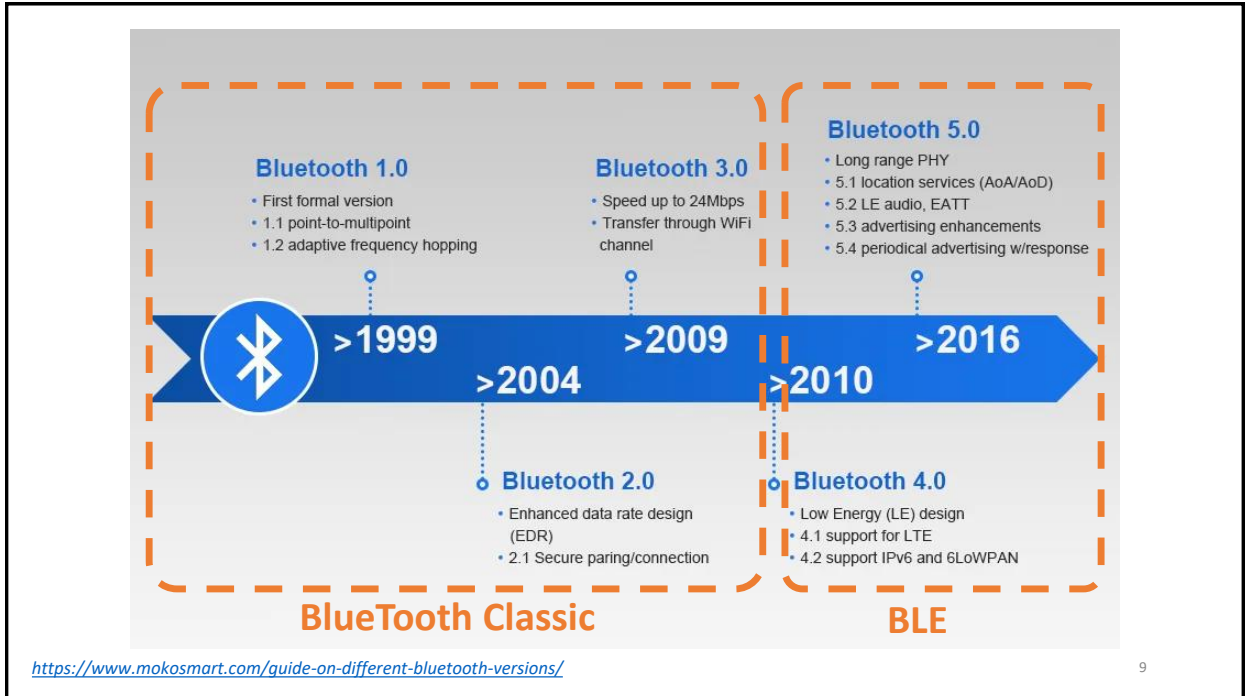


Band
 UHF ISM
 S-Band
S-Band ISM
 C-Band
 C-Band satellite downlink
 C-Band Radar (weather)
 C-Band ISM
 C-Band satellite uplink
 X-Band
 X-Band Radar (police/weather)

Frequency range
 902-928 MHz
 2-4 GHz
2.4-2.5 GHz
 4-8 GHz
 3.7-4.2 GHz
 5.25-5.925 GHz
 5.725-5.875 GHz
 5.925-6.425 GHz
 8-12 GHz
 8.5-10.55 GHz

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BlueTooth

- Bluetooth is a **packet-based protocol** with a master/slave architecture
- One master may communicate with up to 7 slaves in a piconet (ad-hoc computer network using BT technology)
- All devices share the master's clock
- Packet exchange is based on the basic clock (which ticks at 312.5 μ s intervals), defined by the master
- Two clock ticks make up a slot of 625 μ s
- Two slots make up a slot pair of 1250 μ s
- In the case of single-slot packets, the master transmits in even slots and receives in odd slots. The slave, conversely, receives in even slots and transmits in odd slots
- **Packets may be 1, 3 or 5 slots long**, but in all cases the master's transmission begins in even slots and the slave's in odd slots

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BlueTooth – Classic

- Introduced in Bluetooth version 1.0
- Nominal range: 10 cm to 10 meters
- Bluetooth Classic versions are backward compatible
- **79 channels** with 1MHz bandwidth (2.402 – 2.480 GHz)
- One master, up to 7 slaves
- Time (TDMA) and frequency (FHSS) synchronization done by master
- Slave may send data only if polled by master
- Last enhanced version 3.0. still available but not updated any more

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BlueTooth – Classic

- **Frequency-Hopping Spread Spectrum (FHSS)**
 - Radio technology
 - **79 hops (i.e., BT channels)** separated by 1 MHz (i.e., each channel has a bandwidth of 1 MHz)
- Maximum frequency hopping rate: 1600 hops/sec
- Divides transmitted data into packets, and transmits each packet on one of 79 designated BT channels
- One complete data packet can be transmitted within each 625 μ s hop slot

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BlueTooth – BLE

- Bluetooth Low Energy uses 2 MHz spacing, which accommodates 40 channels
- 40 channels with 2 MHz bandwidth (2.402 – 2.480 GHz)
- Lower transmitting power
- Defined from Bluetooth version 4.0 onwards
- Designed for IoT and battery-operated applications
- Bluetooth LE versions are backward compatible
- Mainly short connections (to save battery lifetime)
- **Generic Attribute Profile (GATT)** is a generic “language” between Bluetooth LE devices
- Custom GATT profiles: Amber SPP-like (Serial Port Profile) e.g., Bidirectional transmission of arbitrary data BLE
- Predefined GATT profile:
 - Battery service profile, e.g. Shares value x in percentage 0% (discharged) - 100% (fully charged)
 - Notification service when status changes
 - Link loss service: e.g., Alerts after timeout, or link is lost or user alert

<https://www.bluetooth.com/bluetooth-resources/intro-to-bluetooth-gap-gatt/>
<https://learn.adafruit.com/introduction-to-bluetooth-low-energy/gatt>

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 - Bluetooth vs. Wi-Fi
- BlueTooth Modules
- Example Application + Demo

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Basic Idea

- Bluetooth is a standard for a small, cheap **radio chip** to be plugged into computers, printers, mobile phones, etc.
- Bluetooth chip is designed to replace cables; information is transmitted at a special frequency to a receiver Bluetooth chip.
- These devices can form a quick ad-hoc secure “**piconet**” and start communication.
- Connections in the “piconets” can occur even when mobile.

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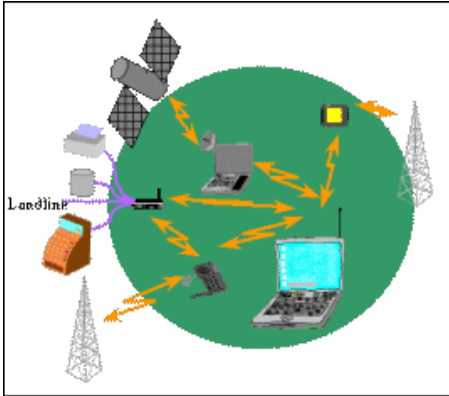
Piconet

- A collection of devices connected via Bluetooth technology in an ad-hoc fashion.
- A **piconet** starts with two connected devices, and may grow to eight connected devices.
- All Bluetooth devices are peer units and have identical implementations. However, when establishing a piconet, one unit will act as a **Master** and the other(s) as **Slave(s)** for the duration of the piconet connection.

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Usage models - Voice/Data Access Points



- Connecting a computing device to a communicating device.
- Allows any device with a bluetooth chip to connect to the internet while located within the range of the access point.
- **Example** - a notebook could link to the internet using a mobile phone as an access point.

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Usage models - Peripheral Interconnects



- Standard peripheral devices like keyboards, mice, headsets, etc. working over a wireless link.
- The same device can be used in multiple functions, e.g., a headset can access phones while in the office and can interface with a cellular phone when mobile.

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Usage models - Personal Area Networking (PAN)



- Allows dynamic formation and breakdown of “PICONETS”: ad-hoc personal networks.

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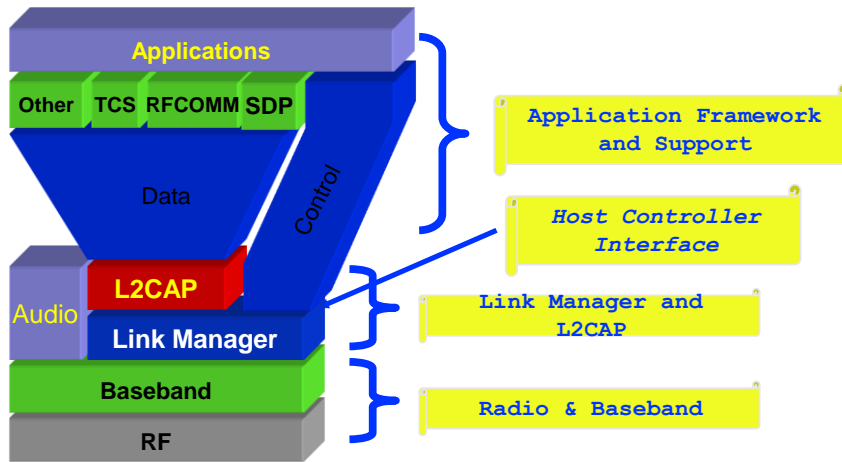
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Bluetooth Protocol Stack

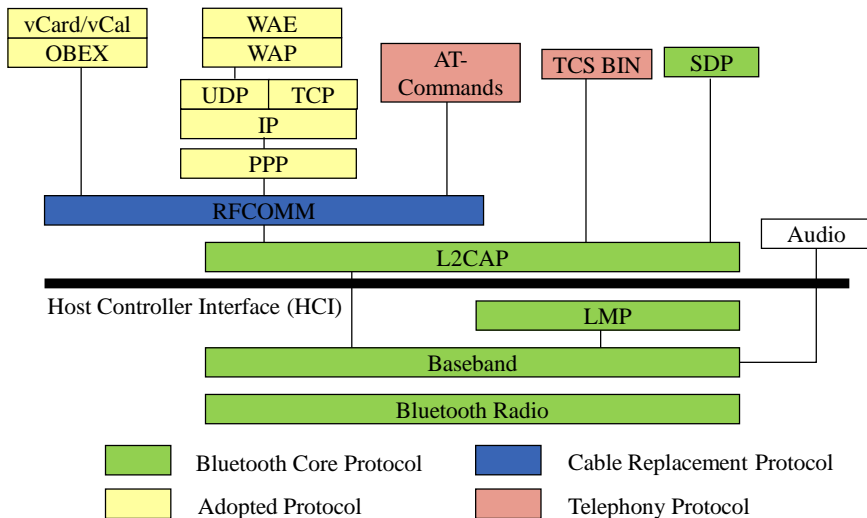


- A hardware/software description
- An application framework

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Bluetooth Protocol Stack - Details



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Layers

- Bluetooth Radio (RF Layer)
- Baseband
- LMP (Link Manager Protocol)
- HCI (Host Controller Interface)
- L2CAP (Logical Link Control and Adaptation Protocol)
- RFCOMM (Radio Frequency Communication)
- SDP (Service Discovery Protocol)

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RF Layer

- The lowest defined layer of the Bluetooth specification
- It defines the requirements of the Bluetooth transceiver device operating in the 2.4 GHz ISM band
- It uses a packet switching protocol based on a technology called **Frequency-hopping spread spectrum (FHSS)** to spread the energy across the ISM band.

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- In order to minimize interference, the nominal antenna power is 1 mW which can be extended to 100 mW.
- The low power limits the range to about 10 centimeters to 10 meters.
- With higher power of 100 mW range of 100 meters can be achieved.
- 3 different power classes
 - Power Class1: long range (100m,100mW)
 - Power Class2: mid range (10m,1-2,5mW)
 - Power Class3: short range (0.1-10m,1mW)

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Frequency-hopping spread spectrum (FHSS)

- **FHSS** is a method of transmitting radio signals by shifting carriers across numerous channels with a pseudorandom sequence which is already known to the sender and receiver.
- Divides the designated range of the ISM-band (2.402GHz to 2.480GHz) into 79 of 1 MHz channels.
- Every frequency is **GFSK** (Gaussian frequency-shift keying) modulated with channel width of 1MHz.

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Frequency-hopping spread spectrum (FHSS)

- A device will use 79 individual (pseudo)randomly chosen frequencies, changing from one to another on a regular basis.
- Communication between devices switches between available channels. The **frequency hopping** is done at a rate of 1600 times a second. This:
 - Allows more devices to use the limited time slice
 - Reduces the chance of two transmitters being on the same frequency at the same time

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Baseband Layer

- The physical layer of the Bluetooth that provides
 - Error correction
 - Flow control
 - Hopping sequence
 - Security
- Hopping through 79 channels
- Data is divided in **packets**
 - Access code: e.g. timing synchronization
 - Header: e.g. packet numbering, flow control, slave address
 - Payload: voice, data or both

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- Connection Modes

- **STANDBY**: not connected in a piconet
- **ACTIVE**: active participation on the channel

- Power Saving Modes

- **SNIFF**: slave listens to the channel at a reduced rate (decreasing of duty cycle) least power efficient
- **HOLD**: data transfer is held for a specific time period, medium power efficient
- **PARK**: synchronized to the piconet but does not participate in traffic

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- Security Modes

- non-secure
- encryption enforced by application layer
- encryption enforced by link layer

- For devices

- trusted device
- untrusted device

- For services

- require authorization and authentication
- require authentication
- open to all devices

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Audio

- Two codecs: PCM and CVSD
- Both at 64kbit/s
- Synchronous Connection Oriented (SCO) links
- Time-critical
- No retransmission
- Errors appear as background noise

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LMP (Link Manager Protocol)

- The Link Manager carries out link setup, authentication, link configuration and other protocols.
- It discovers other remote LM's and communicates with them via the Link Manager Protocol (LMP).
- To perform its service provider role, the LM uses the services of the underlying Link Controller (LC).

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L2CAP (Logical Link Control and Adaptation Protocol)

- L2CAP is layered over the Baseband Protocol and resides in the data link layer
- L2CAP provides connection-oriented and connectionless data services to upper layer protocols with quality-of-service functions using multiplexing, segmentation and reassembly
- Two link types are supported for the Baseband layer:
 - Synchronous Connection-Oriented (SCO)
 - Asynchronous Connection-Less (ACL)

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RFCOMM (Radio Frequency Communication)

- Provides emulation of serial ports
- Supports up to 60 simultaneous connections
- Differentiates between two device types:
 - Type 1: communication end points (e.g. printer or headsets)
 - Type 2: devices which are part of communication (e.g. modems)
- But in the protocol itself no distinction is made, some information is for type 1 other for type 2

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SDP (Service Discovery Protocol)

- Provides a means for applications to discover which services are available and to determine the characteristics of those available services
- Uses a request/response model where each transaction consists of one **request protocol data unit (PDU)** and one **response PDU**
- SDP is used with L2CAP
- Is optimized for the dynamic nature of bluetooth
- SDP does not define methods for accessing services

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Network Topology

- All units have a unique **global ID address** (48 bits)
- The unit that initializes the connection is assigned as the master which controls the traffic of the connection.
- A master can simultaneously connect **up to 7 slaves**.
- A device can be a master in only one “piconet” at a time.
- The master/slave roles can be swapped.

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Network Topology

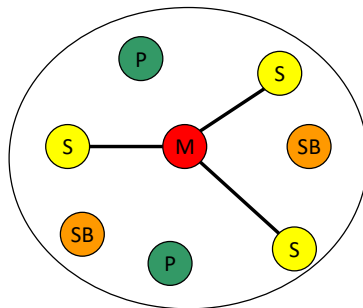
- **Piconet**
 - Each piconet has one master and up to 7 simultaneous slaves
 - **Master**: device that initiates a data exchange
 - **Slave**: device that responds to the master
- **Scatternet**
 - Linking of multiple piconets through the master or slave devices
 - Bluetooth devices have point-to-multipoint capability to engage in Scatternet communication

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Piconet

- All devices in a piconet hop together
 - Master gives slaves its clock and device ID
- Non-piconet devices are in standby



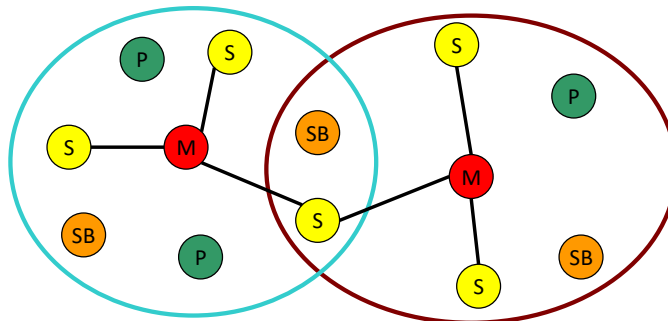
M = Master
P = Parked
S = Slave
SB = Standby

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Scatternet

- Devices can be slave in one piconet and master of another



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Forming a Piconet

- Needs two parameters
 - Hopping pattern of the radio it wishes to connect.
 - Phase within the pattern, i.e., the clock offset of the hops.
- The global ID defines the hopping pattern.
- The master shares its global ID and its clock offset with the other radios which become slaves.
- The global ID and the clock parameters are exchanged using a **FHS (Frequency Hopping Synchronization)** packet.

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- Devices not connected to a piconet are in *STANDBY* mode, using low power.
- A connection is made by either a *PAGE* command if the address is known or by the *INQUIRY* command followed by a *PAGE*
- When a radio sends an *INQUIRY* command, all the listening radios respond with their FHS packets, which tells the inquiring radio of all the radios in the area.
- All listening radios perform a *page scan* and/or an *inquiry scan* every 1.25 seconds.
- The master radio sends an FHS to the paged radio.

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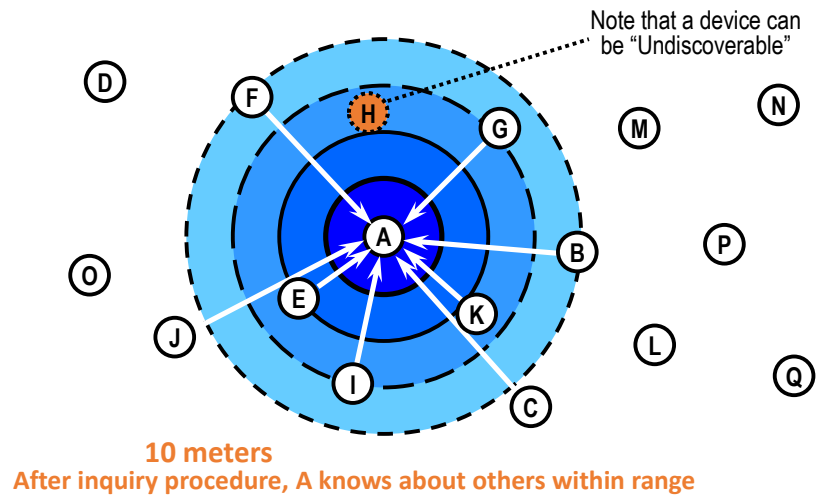
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- When a radio joins a piconet, it is assigned a 3 bit *Active Member Address (AMA)*.
- Once the piconet has eight radios, the master can put/assign a radio into the *PARK* mode.
- This is one of the low power states, in which the radio releases its AMA for a 8 bit *PMA* (Passive Member Address).
- The freed AMA can be assigned to another radio wishing to join the piconet.
- Though up to 256 radios can actively reside on a piconet, only 8 of them with AMA's can transfer data.

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Device Discovery Illustrated



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- Once a radio joins the piconet and has an AMA it can direct data to other devices on the piconet.
- In order to remain in the connected state within a piconet, the radio needs to maintain the frequency hopping pattern and offset while consuming low power.
- To achieve this the connected radios can be placed in either *PARK*, *HOLD* or *SNIFF* modes.

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PARK MODE

- The device has given up the AMA and has become passive.
- The parked device will occasionally listen to see if the master has sent any broadcast data asking it to become active.

HOLD MODE

- When data needs to be transmitted very infrequently, thus conserving power.
- In this mode only an internal timer is running.
- No data is transferred when in HOLD mode.
- The master can put slaves on HOLD mode.

SNIFF MODE

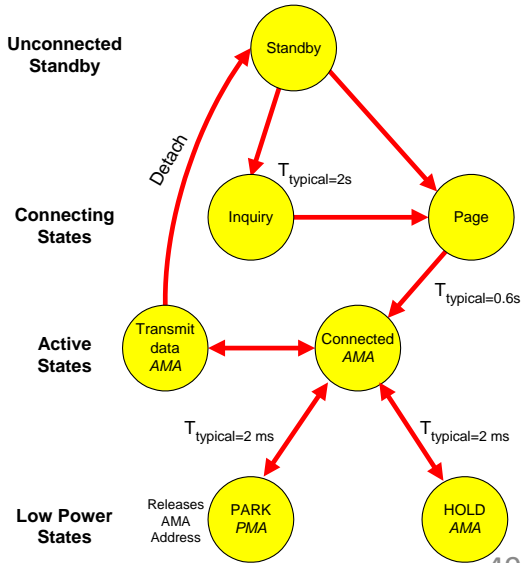
- ❖ A slave device listens to the piconet at a reduced rate.
- ❖ The SNIFF interval is programmable.
- ❖ In both the HOLD and SNIFF states the device retains its AMA.

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Functional Overview

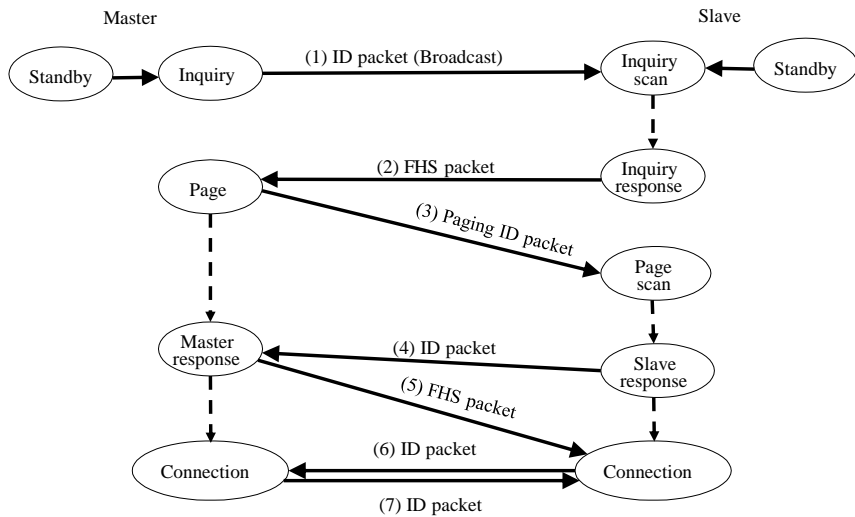
- Standby
 - Waiting to join a piconet
- Inquire
 - Ask about radios to connect to
- Page
 - Connect to a specific radio
- Connected
 - Actively on a piconet (master or slave)
- Park/Hold
 - Low Power connected states



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Connection: Inquiry and Paging



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Two Types of Links

- Baseband Layer handles two types of links:

- Synchronous Connection Oriented (SCO)

- Support symmetrical, circuit-switched, point-to-point connections
 - Typically used for voice traffic; do not use CRC and are not retransmitted
 - Data rate is 64 kbit/s

- Asynchronous Connection-Less (ACL)

- Support symmetrical and asymmetrical, packet-switched, point-to-multipoint connections
 - Typically used for data transmission
 - Up to 433.9 kbit/s in symmetric or 723.2/57.6 kbit/s in asymmetric

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- Bluetooth Modules

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Security

- Bluetooth relies on **PIN codes** to establish trusted relationships between devices
- Supports Unidirectional or Mutual Encryption based on a secret link Key (128 bit) shared between two devices
- Security defined in **3 modes**
 - Mode1 - No security
 - Mode 2 - Service level security: not established before channel is established at L2CAP
 - Mode 3 - Link level security: device initiates security before LMP (link management protocol) link is setup
- Devices and Services can be Set for Different Levels of Security
 - Two Trust Levels are Set for Devices
 - **Trusted Device**: Fixed Relationship and Unrestricted Access to All Services
 - **Untrusted**: No Permanent relationship and Restricted Services

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Antennas

- Internal antennas
- External antennas



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BlueTooth vs. Wi-Fi

- Similar applications

- Setting up networks, printing, or transferring files

- Bluetooth

- Intended for portable equipment and its applications (wireless personal area network, WPAN); ad-hoc connections
- Also works for fixed location applications such as smart energy functionality in homes (thermostats, etc.)
- Usually symmetrical, between two Bluetooth devices
- Simple applications: headsets, remote controls, etc.

- Wi-Fi

- Intended as replacement for high-speed cabling (wireless local area networks, WLAN)
- Usually access point-centered, with asymmetrical client-server connection with all traffic routed through the access point
- Applications where high speeds are required, especially for network access 55

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BlueTooth vs. Wi-Fi

Figure 1.
Select the Best Wireless Standard for Your Application

	ZigBee 802.15.4	Bluetooth 802.15.1	Wi-Fi 802.11b	GPRS/GSM 1XRTT/CDMA
System resource	4-32 KB	250 KB+	1 MB ±	16 MB+
Battery life (days)	100-1,000+	1-7	0.1-5	1-7
Nodes per network	255/65,000+	7	30	1-1000
Bandwidth (KBps)	20-250	720	11,000+	64-128
Range (meters)	1-75+	1-10+	1-100	1000+

Figure 2.
Which Wireless Standard?

	Application Focus	Success Metrics
ZigBee	Monitoring and control	Reliable, secure networking Protocol simplicity Low power consumption
Bluetooth	Cable replacement	Low incremental cost Ease of use/convenience Moderate data rate
Wi-Fi	Web, email, and video	High data throughput Flexibility (work and home) Hot Spot connectivity
GPRS / GSM	Wireless voice and data	Broad geographic coverage Datacentric pricing plans Network build-out

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Outline

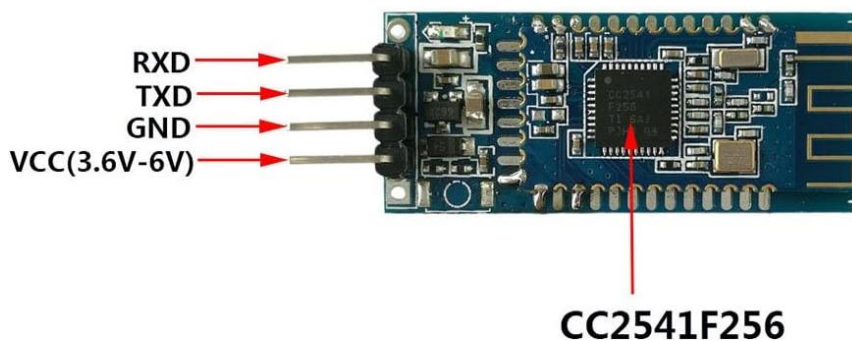
- Bluetooth
- **Bluetooth Modules**
- Example Application + Demo

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Bluetooth Modules: **HM-10**

- **HM-10** Bluetooth Module
 - <https://www.deshide.com/product-details.html?pid=344851&t=1665210577>
- Bluetooth Specification v4.0 BLE (can be discovered by iPhone)



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Texas Instruments BLE Chip – CC2541



CC2541

2.4-GHz Bluetooth™ low energy and Proprietary System-on-Chip
Check for Samples: CC2541

FEATURES

- 2.4-GHz Bluetooth low energy Compliant and Proprietary RF System-on-Chip
- Supports 250 kbps, 500 kbps, 1 Mbps, 2-Mbps Data Rates
- Excellent Link Budget, Enabling Long-Range Applications Without External Front End
- Programmable Output Power up to 0 dBm
- Excellent Receiver Sensitivity (-94 dBm at 1 Mbps), Selectivity, and Blocking Performance
- Suitable for Systems Targeting Compliance With Worldwide Radio Frequency Regulations: ETSI EN 300 328 and EN 300 440 Class 2 (Europe), FCC CFR47 Part 15 (US), and ARIB STD-T66 (Japan)
- Layout
 - Few External Components
 - Reference Design Provided
 - 6-mm x 6-mm QFN 40 Package
 - Pin-Compatible With CC2540 (When Not Using USB or PC)
- Low Power
 - Active-Mode RX Down to: 17.9 µA
 - Active-Mode TX (0 dBm): 18.2 mA
 - Power Mode 1 (4-µs Wake-Up): 270 µA
 - Power Mode 2 (Sleep Timer On): 1 µA
 - Power Mode 3 (External Interrupts): 0.5 µA
 - Wide Supply Voltage Range (2 V–3.6 V)
- TPS62730 Compatible Low Power in Active Mode
 - RX Down to: 14.7 mA (3-V supply)
 - TX (0 dBm): 14.3 mA (3-V supply)
- High-Performance and Low-Power 8051 Microcontroller Core With Code Prefetch
- In-System Programmable Flash, 128- or 256-Kbit
- 8-Kbit RAM With Retention in All Power Modes
- Hardware Debug Support
- Extensive Baseband Automation, Including Auto-Acknowledgment and Address Decoding
- Retention of All Relevant Registers in All Power Modes
- Peripherals
 - Powerful Five-Channel DMA
 - General-Purpose Timers (One 16-Bit, Two 8-Bit)
 - IR Generation Circuitry
 - 32-KHz Sleep Timer With Capture
 - Accurate Digital RSSI Support
 - Battery Monitor and Temperature Sensor
 - 12-Bit ADC With Eight Channels and Configurable Resolution
 - AES Security Coprocessor
 - Two Powerful USARTs With Support for Several Serial Protocols
 - 23 General-Purpose I/O Pins (21 × 4 mA, 2 × 20 mA)
 - PC Interface
 - 2 I/O Pins Have LED Driving Capabilities
 - Watchdog Timer
 - Integrated High-Performance Comparator
- Development Tools
 - CC2541 Evaluation Module Kit (CC2541EMK)
 - CC2541 Mini Development Kit (CC2541DK-MINI)
 - SmartRF™ Software
 - IAR Embedded Workbench™ Available

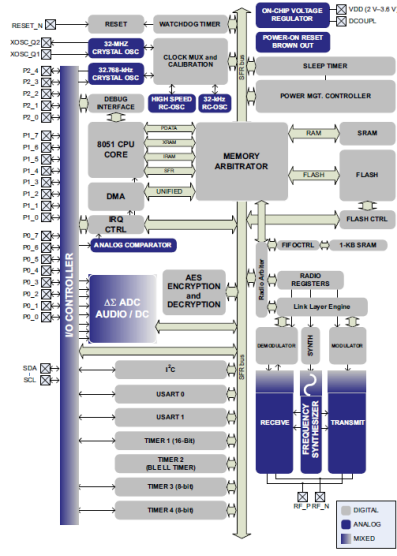


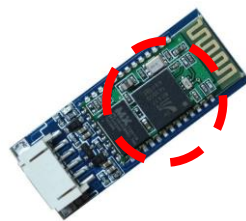
Figure 1. Block Diagram

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Bluetooth Modules: HC-06

- JY-MCU BT_BOARD V1.07 - referred to as **HC-06 Module**
 - Manual: http://www.ram-e-shop.com/ds/general/Bluetooth_TRx_Module_New.pdf
 - There are many similar others (including HC-03, HC-04, and HC-05)
- Wireless Bluetooth Transceiver Module – uses Bluetooth Specification v2.0 (not supported by iPhones)
- Can work either as a master or a slave
- Built around the **BC417 Bluetooth-to-Serial** chip

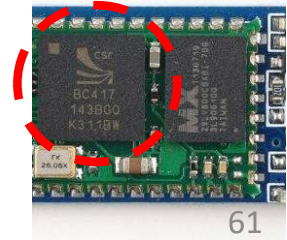
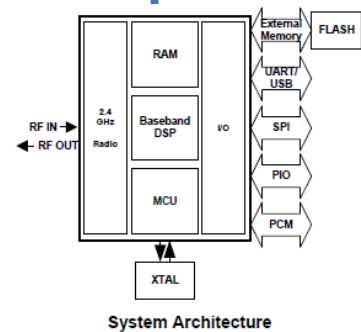


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BC417 BlueTooth-to-Serial Chip

- Single chip radio and baseband IC for Bluetooth 2.4 GHz systems
 - Datasheet: <https://cdn.sparkfun.com/datasheets/Wireless/Bluetooth/CSR-BC417-datasheet.pdf>
- Enhanced data rates (EDR) to 3Mbps
- Loaded with features
 - 1.8V core, 1.8 to 3.6V I/O
 - UART interface with programmable baud rate up to 3M baud
 - Low Power 1.8V operation
 - USB and Dual UART Ports
 - By default, it works as a Slave, 9600 baudrate, N, 8, 1, and Pincode 1234



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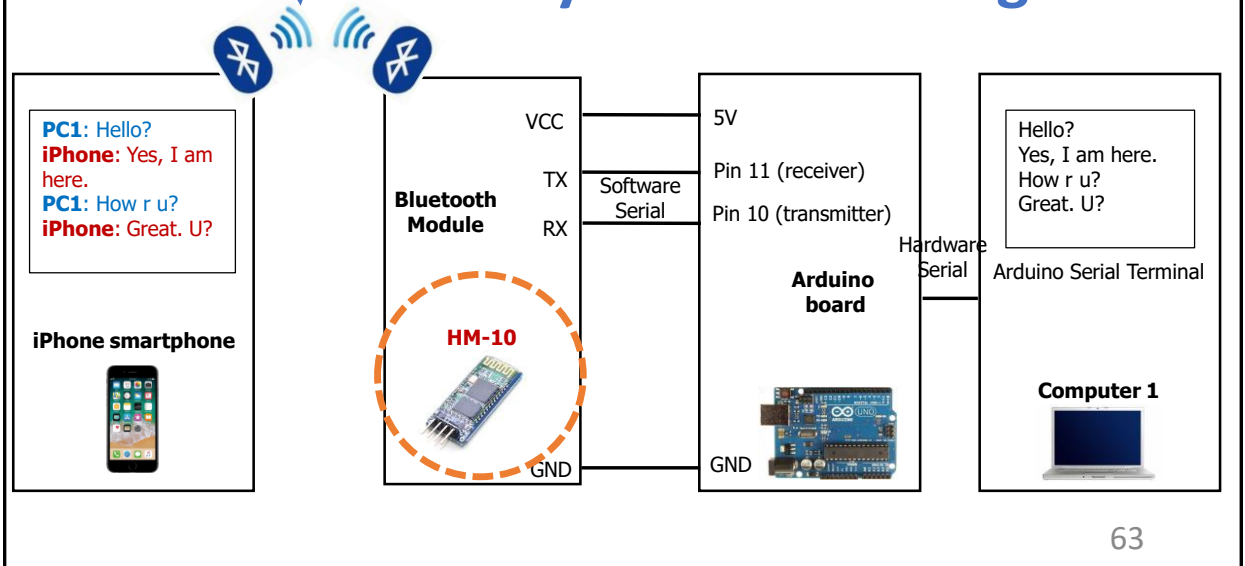
Outline

- Bluetooth
- Bluetooth Modules
- Example Application + Demo

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Chat System – System Level Diagram



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Credits and References

- <https://en.wikipedia.org/wiki/Bluetooth>
- <https://www.bluetooth.com/learn-about-bluetooth/tech-overview/>
- http://www.radio-electronics.com/info/wireless/bluetooth/bluetooth_overview.php
- <https://www.bluetooth.com/wp-content/uploads/Files/Specification/HTML/Core-54/out/en/host-controller-interface/host-controller-interface-functional-specification.html>

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